Oward future-Oriented Road Surface Monitoring

NETIS

ACTUS Wireless IRI Measuring System

[Advanced Compact Telecommunication Unwired-accelerometer System]



The Simple, Convenient, and Accurate IRI measurement

- * Simply press Start and Stop to take IRI measurements *Easy to install, even on passenger vehicles
- *Enjoy more accurate monitoring with a structure based solely on IRI principles
- A Quickly evaluate road surfaces with real-time monitoring
- ★Obtain positional information even in tunnels and other places Where no satellite signals are received



AGTUS (a simple IRI measurement system)

- The International Roughness Index (IRI) was proposed in 1986 by the World Bank as a metric for linking pavement performance to motorist comfort.
- •Japan has required the use of IRI to evaluate the longitudinal roughness of road surfaces since the February 2013 publishing of the Sotenken jisshi yoryo (an) hoso hen (The Implementation guideline on general inspections(proposed)for pavement).
- ACTUS is a simple IRI measurement system that makes it possible to obtain data about road surfaces from regular vehicles wirelessly and while in motion from sensors installed on the vehicles. We can expect this technology to enable data acquisition at high frequencies, improve economic efficiency and workability, shorten work schedules, and limit negativeimpacts on the global environment.

Remarks

UACTUS was jointly developed by the Kitami Institute of Technology, Tokyo University of Agriculture, PROFICT LAB Co., Ltd., Kotobuki Engineering Co., Ltd., and NEWJEC Inc.

②ACTUS was part of an event for matching needs to technology seeds hosted by the Kinkl Regional Development Bureau of the Ministry of Land. Infrastructure, Transport and Tourism.
③An industry-academia consortium was launched for the Mobile ProfiloMeter (MPM) pilot project.

•Key Features ulletAcceleration sensors mounted on sprung mass and on unsprang mass of vehicle send data wirelessly to the main unit (no need to connect the sensors to the interior) Obtains positional information from GPS and vehicle speed pulses •Sensors extract vehicle speed pulses and relay them to the main unit, making it possible to obtain positional information inside tunnels and other places where no satellite signals are received Enables real-time monitoring from computers by combining road surface data with positional information Plots measurements on maps and drawings System configuration (Installation locations) Main unit GPSantenna Data transmitted from the sensors to the main unit over a wireless network (Zigbee) * Laptop or tablet (separate preparation required) ACTUS電源コード * Acceleration sensors can source their Installation location of lower sensor Installation location of upper sensor electric power from dry batteries or by _ _ _ _ _ _ _ _ _ connecting to the vehicle battery. ACTUS main unit Built-in gyrosensor •Built-in wireless module (IEEE802.15.4: Zigbee) •Built-in GPS module (GV-87 evaluation kit) Acceleration sensors •Built-in wireless module (IEEE802.15.4: Zigbee) •Acceleration sensor ADXL345 (triaxial) ACTUS main unit An acceleration sensor Frequency: 800 Hz (with built-in gyrosensor) (5-cm opening, 2 cm thick) *If requested, we install and calibrate the equipment (consultation required).

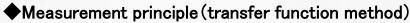
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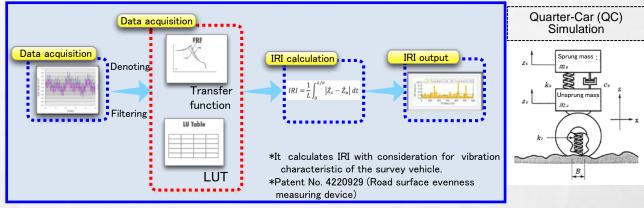
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Oward future-Oriented Road Surface Monitoring

Toward future-Oriented Road Surface Monitoring





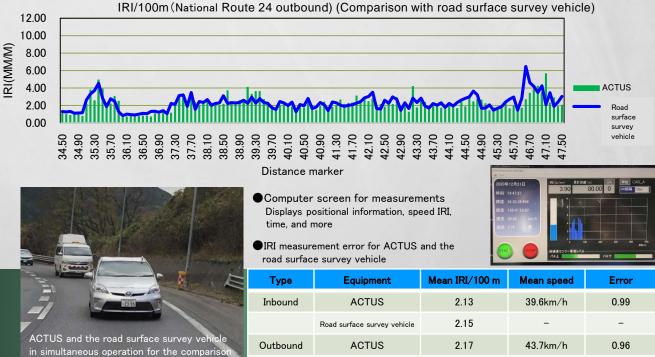
Performance

Demonstrates Class-2 performance as described in the Pavement Survey/Test Method Manual (2019 version).

| Class | Method of measuring surface roughness | IRI calculation method | Method of application |
|-------|---|---|--|
| 1 | Rod and Level measurement IRI is calculated based on QC simulations after measuring longitudinal roughness with a level or the like Measurement | | |
| | Laser displacement sensor | IRI is calculated based on QC simulations after measuring longitudinal roughness with a laser displacement | Road surface survey vehicle |
| | Accelerometers mounted on sprung Mass and unsprang mass | sensor IRI is calculated with sprung/unsprung mass accelerometers in the course of transfer function correction based on IRI principles (QC simulation) | ACTUS |
| | | | Smartphone, etc. |
| 4 | Physical sensations and visual confirmation by surveyors riding in patrol cars or the like | equation IRI is presumed and quantified based on ride experience and visual inspection on patrol cars | Physical sensations, visual confirmation |

Quality of measurement

ACTUS was part of an event for matching needs to technology seeds hosted by the Kinki Regional Development Bureau of the Ministry of Land, Infrastructure, Transport and Tourism in 2020, where it was compared to the road surface survey vehicle used in regular road surface inspections, and performed favorably in terms of economic efficiency, work processes, quality of the final results, safety, and workability.



Road surface survey vehicle

2.27



Options

•Plotting IRI measurements on maps:

⇒The system uses GIS to plot measurements on maps for identification of damaged section.

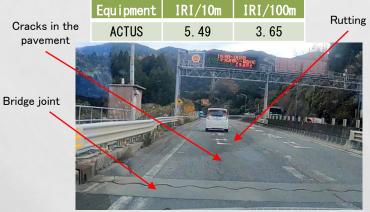


Product specification

| Measurement ranges | Speed rage: 20 to 120 km/h ,Public roads, Operating temperature range: –20 to +85 $^\circ$ C | | |
|---------------------------|---|--|--|
| System requirements | OS: Windows 8/10 (64-bit), Memory: At least 4 GB | | |
| Sensor power source | Dry batteries Vehicle battery | Three AA batteries (Battery life: Approximately 20 hours/Type: Alkaline) Power cable that connects to vehicle battery | |
| Equipment and accessories | upment and accessories Main measuring unit, acceleration sensors (2), external battery box, power cable for connu vehicle battery, USB cable, point recording device, vehicle speed signal cable, GPS anten ROM (driver), instruction manual | | |

Using action cameras to verify the condition of road surfaces

• Installing an action camera (e.g. GoPro) separate from the system and taking simultaneous measurements makes it possible to verify the consistency of ACTUS results with the condition of road surfaces.



Photograph of the condition of the road surface

Camera position

Contact for inquiries

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Technology in harmony with Nature and People

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